



# Taking fragile communication means into account for stream programs

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CEA, LIST—January 24th, 2017

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## 1 Context

- Stream programming and parallel distributed systems
- Stream programming, principles and models
- Graph model, properties and optimization

## 2 The case of fragile communication links

- Scheduling approach, case of (C)SDF
- A new model for stream programs: TPDF

## 3 Conclusion

Parallel distributed embedded applications cumulate several issues:

- Parallelism
- Communication between sub-parts / sub-systems
- Possibly mixed criticality
- Heterogeneity of resources

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- Parallelism
- Communication between sub-parts / sub-systems
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Stream programming solves some of these issues:

- Simple programming model
- Parallelism and synchronization points are obvious both to the programmer and to the compiler
- Compilation tools can offer powerful optimization scenarios
- Most of broadly used stream programming models are deterministic and are well fit to DSP and video processing applications
- amenable to real-time constraints

The base is a directed graph  $(A, E, T)$

- $A$  a set of Actors
- $E$  a set of directed edges in  $A \times A$
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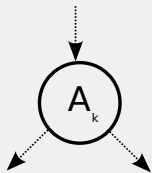
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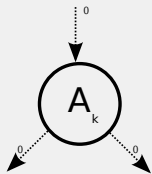
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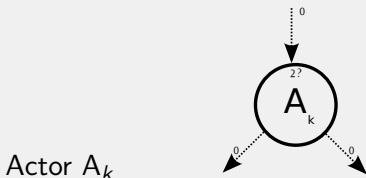


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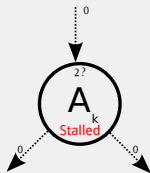


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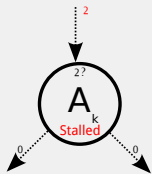
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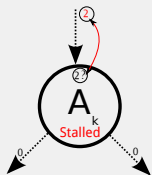
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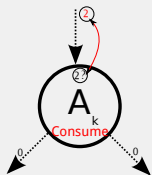
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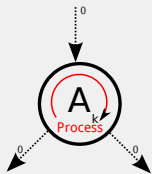
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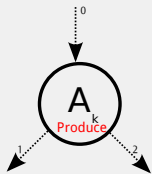
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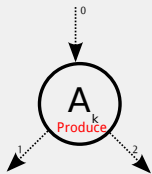
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## Actors



Actor  $A_k$

Locally deterministic



Several Models of Computation are available:

- KPN: firing rules can change freely according to the program encapsulated within the actor
- HDF: firing rules are static allowing for production and consumption of a single data token for each link
- CSDF: static firing rules are triggered according to a fixed size cycle
- SADF: commutations of firing rules according to a fixed set of scenarios
- BDF: control link allow for switching between branches
- etc.

Analizability of the MoC depends on the model. The nicest ones provide guaranties against deadlocks, livelocks and inconsistencies.

The graph structure allows for:

- A hierarchical definition of an application
- A set of graph transformations: coarsening, some rules of permutations or rewriting (i.e. optimization)
- A graphical representation showing in an obvious way where are the performance pitfalls
- Partitioning: good for heterogeneous computing

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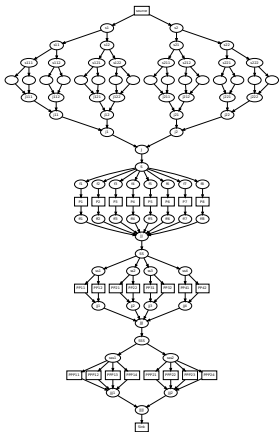
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SDF and CSDF models are often used when safety is important:

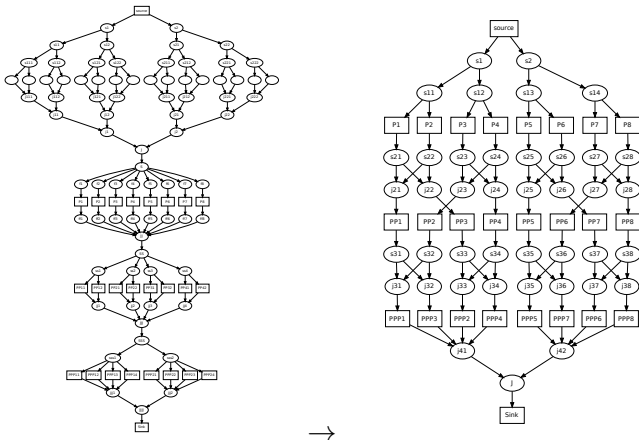
- Deadlock and livelock free
- Amenable to real-time constraints (RT scheduling)
- Some extensions aim to extend the expressiveness of the models

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Usual assumptions of stream programming:

- Actors have WCETs
- Communication links are robust and preserve order

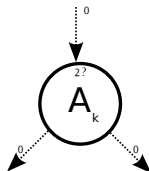
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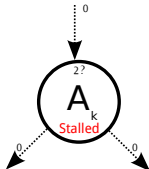
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- IoT and Home automation
  - Autonomous vehicles (e.g. traffic aware navigation)
  - Smart grids
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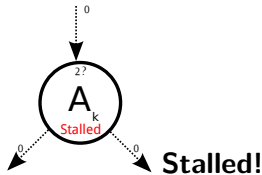
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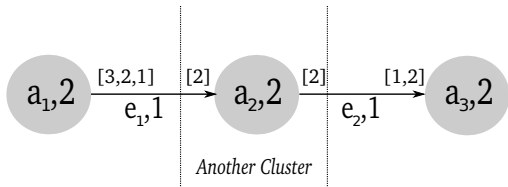


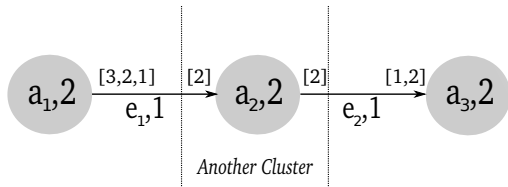
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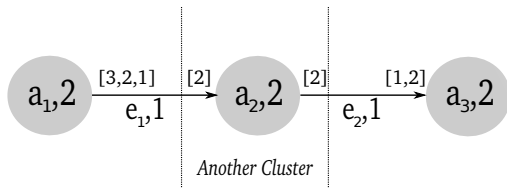
# A scheduling approach for distributed systems





First idea: token matching with time stamping

$a_1$	$a_2$	$a_3$
1	1	1
2	2	2
		3
3	3	4



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For CSDF there exist 2 minimal repetition vectors:

$$\vec{r} = [1, 3, 2] \quad \text{and} \quad \vec{q} = [3, 3, 4]$$

These provide basis of all well-formed scheduling policies

$$\Gamma \cdot \vec{r} = 0, \quad (1)$$

where  $\Gamma$  is the *topology matrix* of  $G$ .

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Period vector:

$$\lambda_i^{min} = \frac{Q}{q_i} \left\lceil \frac{\eta}{Q} \right\rceil \quad \text{for } a_i \in A, \quad (2)$$

where  $\eta = \max_{a_i \in A}(\omega_i q_i)$  and  $Q = lcm(q_1, q_2, \dots, q_n)$

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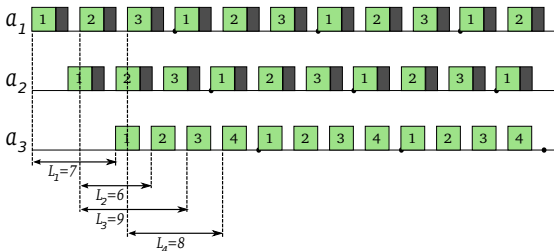
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$$ADF_{A \leftarrow B}(n) = \max_{\phi \in \Phi} \text{List}(|\phi \wedge A(n)| \wedge \{B\})$$

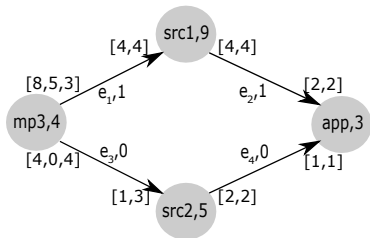
where  $\phi$  is an ordered sequence of actor firings of a dataflow graph and  $\Phi$  denotes the set of all legal schedules.

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Definition of a “Late schedule”: fire Actors as late as possible

```
1: //Late Schedule: X predecessors are fired as late as possible
2: lateSchedule(X,n) {
3:    $\phi = \{\}$ 
4:   for  $i = 1$  to  $n$  do
5:     for all input channels  $c_i$  of  $X$  do
6:       while  $X$  need more tokens on  $c_i$  in order to fire do
7:         //extend schedule ( $\oplus$  denotes concatenation)
8:          $\phi = \phi \oplus \text{lateSchedule}(\text{source}(c_i), 1)$ 
9:       end while
10:    end for
11:    //add  $X$  to schedule
12:     $\phi = \phi \oplus X$ 
13:    //update number of tokens on I/O channels of  $X$ 
14:    simulateExecution( $X$ )
15:  end for
16:  return  $\phi$  }
```

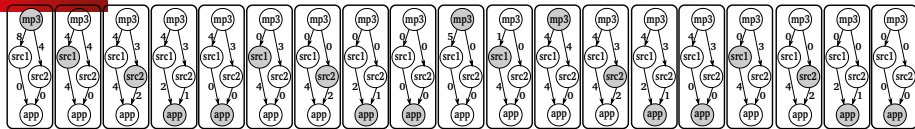


And the data dependence:

mp3	src1	src2	app
1	1	1	1
			2
	2	2	3
			4
2	3		
3		3	5
			6
	4	4	7
			8

# Scheduling and Actor Dependence Function (ADF)

list  
c2tech



mp3	src1	src2	app	app	src1	src2	app	app	mp3	src1	mp3	src2	app	app	src1	src2	app	app
-----	------	------	-----	-----	------	------	-----	-----	-----	------	-----	------	-----	-----	------	------	-----	-----

Count the ordinal number of executions  
for each actor in Late schedule

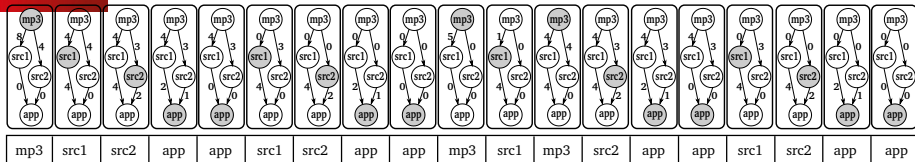
1	1	1	1	2	2	2	3	4	2	3	3	3	5	6	4	4	7	8
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

$ADF_{mp3 \leftarrow app}(1) = \{1, 2, 3, 4\}$				$ADF_{mp3 \leftarrow app}(2) = \{\}$				$ADF_{mp3 \leftarrow app}(3) = \{5, 6, 7, 8\}$					
--	--	--	--	--------------------------------------	--	--	--	--	--	--	--	--	--

$ADF_{src2 \leftarrow app}(1) = \{1, 2\}$				$ADF_{src2 \leftarrow app}(2) = \{3, 4\}$				$ADF_{src2 \leftarrow app}(3) = \{5, 6\}$				$ADF_{src2 \leftarrow app}(4) = \{7, 8\}$			
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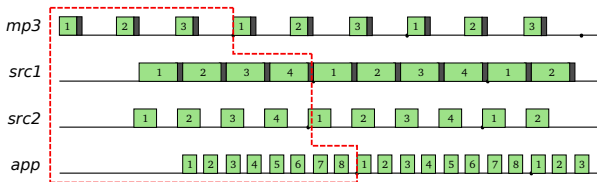
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-----	------	------	-----	-----	------	------	-----	-----	-----	------	-----	------	-----	-----	------	------	-----	-----

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1	1	1	1	2	2	2	3	4	2	3	3	3	5	6	4	4	7	8
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

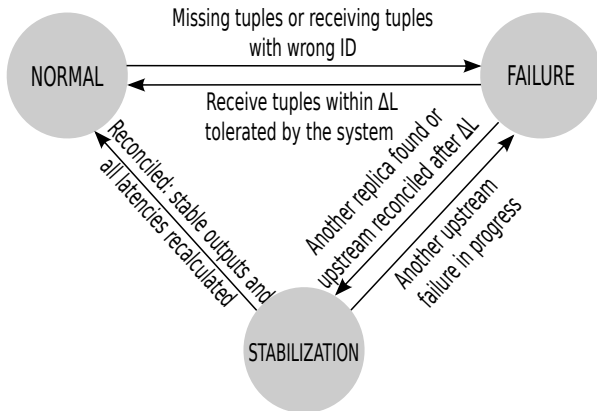
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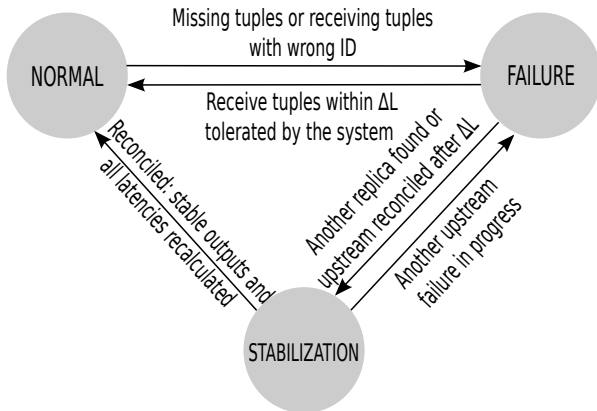




Model of fault tolerance within CSDF:



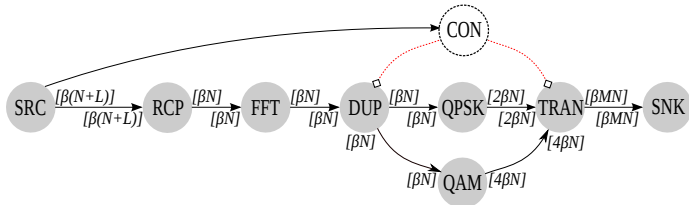
Model of fault tolerance within CSDF:



Alternatively: Modify the MoC to take uncertainties into account  $\rightarrow$  TPDF

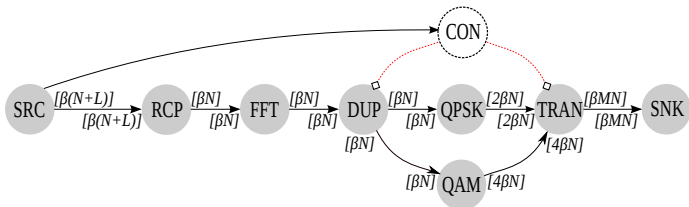
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- Dynamic rates in embedded applications: e.g. SW radio

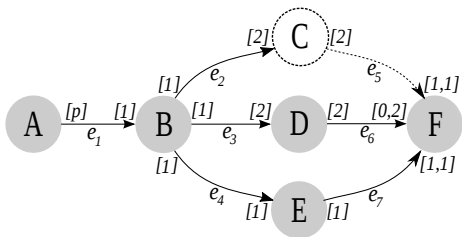


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- Multiple path with fragile timing:



TPDF is:

- globally deterministic
- RT aware
- Amenable to fault-tolerance

On going work, but well-fitted to Mixed Criticality systems

Stream programming is a good model for embedded and distributed applications

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- Amenable to RT constraints
- Lots of optimization and transformations on graph constructs

But requires improvements:

- For fragile communications
- For scheduling

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Future work:

- Improve the model: TPDF as one possible way
- Parameters
- Checkpoints (“Transaction”) with control actors to check timing and change the execution state of the application

# Thanks!

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